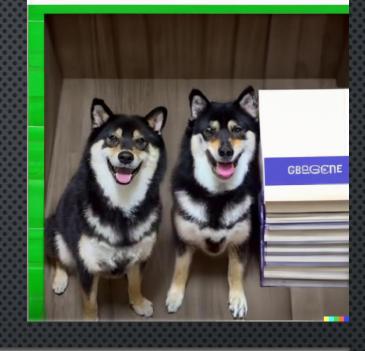
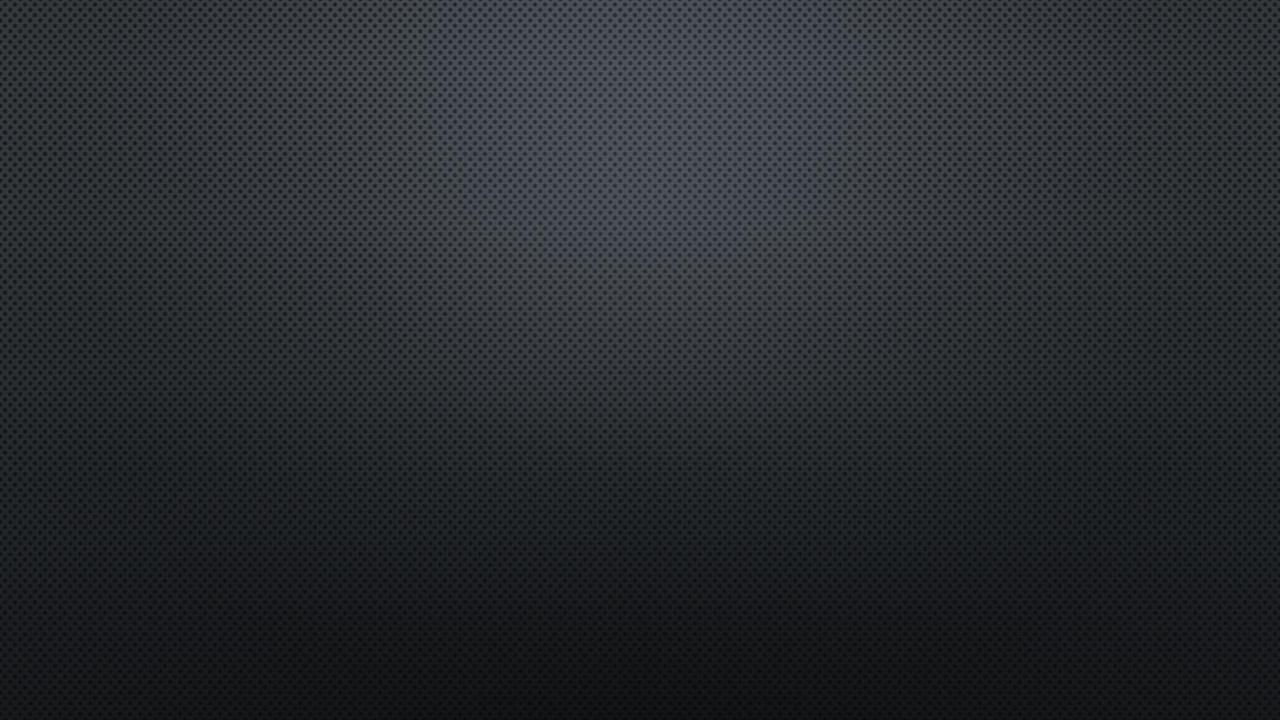
## AI人工智慧— 進階CNN卷積神經網路



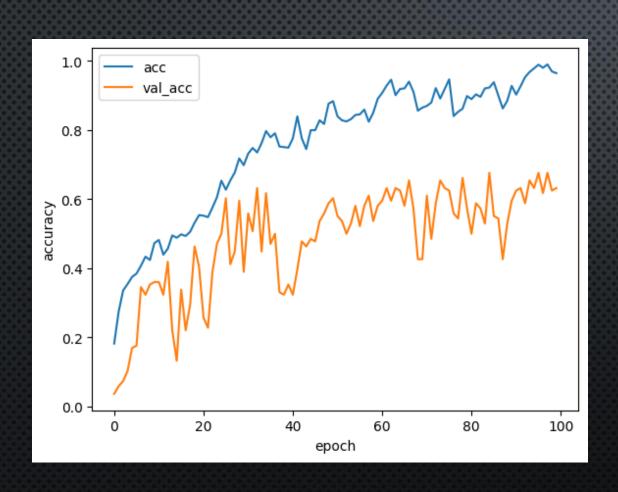


所謂進階CNN卷積神經網路learning by doing

von anwendeng



## 針對oxflower17的訓練成果,當然有進步的空間





predict: [ 5 16 14 9 14 7 14 6 14 0 7 12 4 5 1 8 1 3 6 9 4 3 14 10
 9]
true value: [ 5 16 14 9 14 7 16 6 14 0 7 12 3 5 1 15 1 3 6 4 4 3 14 10
 9]

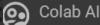


• By Cmglee - Own work, CC BY-SA 4.0, https://commons.wikimedia.org

#### AlexNet Image: 224 (height) × 224 (width) × 3 (channels) Convolution with 11×11 kernel+4 stride: 54×54×96 ReLu Pool with 3×3 max. kernel+2 stride: 26×26×96 Convolution with 5×5 kernel+2 pad:26×26×256 ReLu Pool with 3×3 max.kernel+2stride: 12×12×256 Convolution with 3×3 kernel+1 pad:12×12×384 ReLu Convolution with 3×3 kernel+1 pad:12×12×384 /ReLu Convolution with 3×3 kernel+1 pad:12×12×256 /ReLu Pool with 3×3 max.kernel+2stride: 5×5×256 / flatten Dense: 4096 fully connected neurons ReLu, dropout p=0.5 Dense: 4096 fully connected neurons ReLu, dropout p=0.5 Dense: 1000 fully connected neurons Output: 1 of 1000 classes

## from sklearn.model\_selection import train\_test\_split

# 使用 train\_test\_split 函數將數據集分割為訓練集和測試集
 from sklearn.model\_selection import train\_test\_split
 X\_train, X\_test, Y\_train, Y\_test = train\_test\_split(X, Y, test\_size=0.2, random\_s)



您也可以使用其他套件將數據集分割為訓練集和測試集。例如,您可以使用 numpy 套件中的 split 函數。

```
import numpy as np

# 將數據集分割為訓練集和測試集
X_train, X_test, Y_train, Y_test = np.split(data, [i])

Use code with caution
```

#### 其中:

- data 是數據集
- X\_train 是訓練集的特徵集
- X test 是測試集的特徵集

```
您也可以使用 pandas 套件中的 train_test_split 函數。

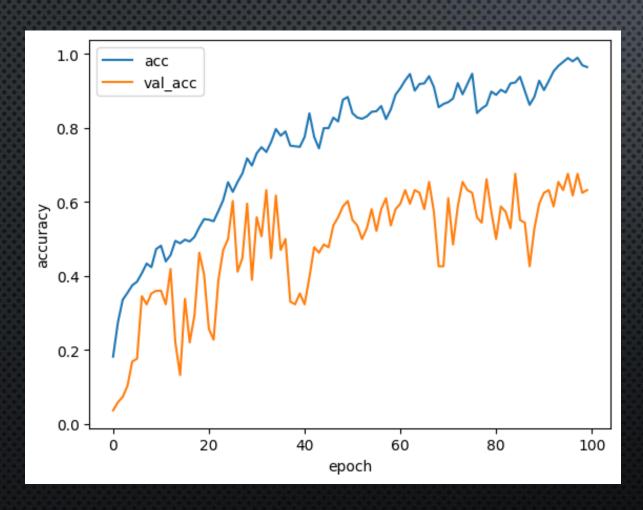
import pandas as pd

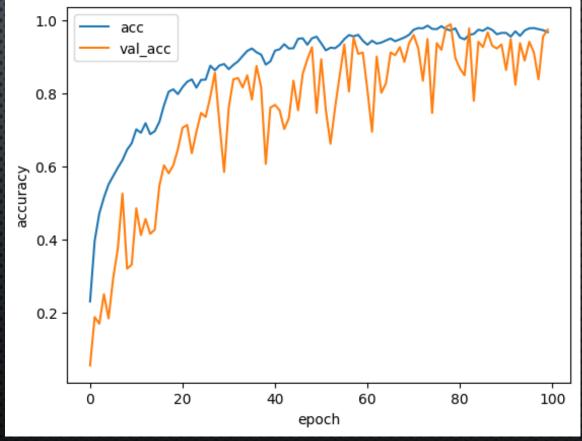
# 將數據集分割為訓練集和測試集
X_train, X_test, Y_train, Y_test = pd.train_test_split(data,
```

## from keras.preprocessing.image import ImageDataGenerator

```
keras.preprocessing.image import ImageDataGenerator
    使用 ImageDataGenerator 進行數據擴增
   datagen = ImageDataGenerator(
         horizontal_flip=True, # 左右鏡射
         rotation_range=30, # 旋轉30度
          zca_whitening=False, # 不進行 ZCA 白化處理
         featurewise center=True # 進行特徵均值中心化
6
```

## V1 vs V2





### **Keras Applications**

Keras Applications are deep learning models that are made available alongside pre-trained weights. These models can be used for prediction, feature extraction, and fine-tuning.

Weights are downloaded automatically when instantiating a model. They are stored at ~/.keras/models/.

Upon instantiation, the models will be built according to the image data format set in your Keras configuration file at ~/.keras/keras.json. For instance, if you have set image\_data\_format=channels\_last, then any model loaded from this repository will get built according to the TensorFlow data format convention, "Height-Width-Depth".

#### Available models

Model	Size (MB)	Top-1 Accuracy	Top-5 Accuracy	Parameters	Depth	Time (ms) per inference step (CPU)	Time (ms) per inference step (GPU)
Xception	88	79.0%	94.5%	22.9M	81	109.4	8.1
VGG16	528	71.3%	90.1%	138.4M	16	69.5	4.2
VGG19	549	71.3%	90.0%	143.7M	19	84.8	4.4
ResNet50	98	74.9%	92.1%	25.6M	107	58.2	4.6
ResNet50V2	98	76.0%	93.0%	25.6M	103	45.6	4.4

VGGNet使用3x3的filer size,的filer size,以及把深度加深,論文中提到總共有11~19的深度,其中以Vgg-16、Vgg-19效果最好。VGGNet在2014年ILSVRC的分類比賽中拿到亞軍

## VERY DEEP CONVOLUTIONAL NETWORKS FOR LARGE-SCALE IMAGE RECOGNITION

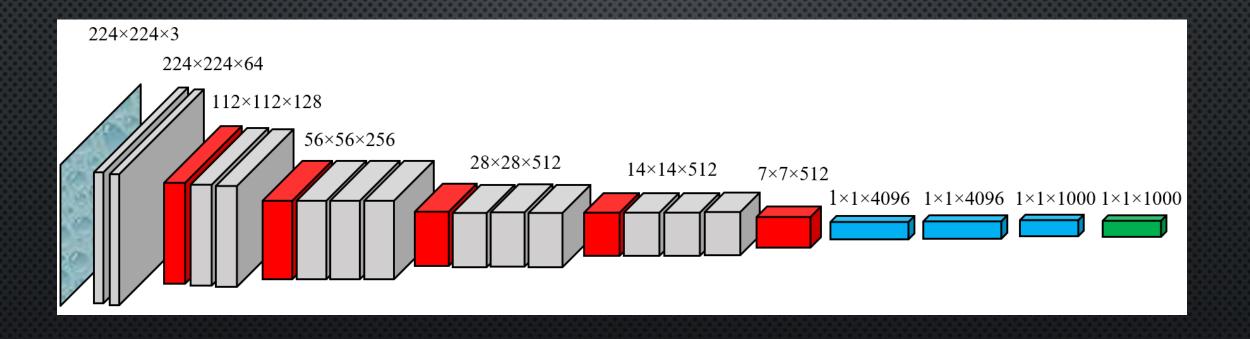
#### Karen Simonyan\* & Andrew Zisserman+

Visual Geometry Group, Department of Engineering Science, University of Oxford {karen,az}@robots.ox.ac.uk

#### **ABSTRACT**

In this work we investigate the effect of the convolutional network depth on its accuracy in the large-scale image recognition setting. Our main contribution is a thorough evaluation of networks of increasing depth using an architecture with very small (3  $\times$  3) convolution filters, which shows that a significant improvement on the prior-art configurations can be achieved by pushing the depth to 16–19 weight layers. These findings were the basis of our ImageNet Challenge 2014 submission, where our team secured the first and the second places in the localisation and classification tracks respectively. We also show that our representations generalise well to other datasets, where they achieve state-of-the-art results. We have made our two best-performing ConvNet models publicly available to facili-

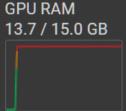
#### https://en.wikipedia.org/wiki/File:VGG\_neural\_network.png



## CNN模型使用仿VGG

```
loss: 0.1476 - acc: 0.9559 - val_loss: 0.0947 - val_acc: 0.9706 - lr: 1.1790e-06
loss: 0.1433 - acc: 0.9603 - val_loss: 0.0957 - val_acc: 0.9706 - lr: 1.1790e-06
loss: 0.1355 - acc: 0.9566 - val_loss: 0.0904 - val_acc: 0.9706 - lr: 1.0611e-06
loss: 0.1818 - acc: 0.9507 - val_loss: 0.0925 - val_acc: 0.9706 - lr: 1.0611e-06
loss: 0.1620 - acc: 0.9463 - val_loss: 0.0928 - val_acc: 0.9706 - lr: 9.5501e-07
:: 0.1636 - acc: 0.9375
```





磁碟 27.1 / 78.2 GB

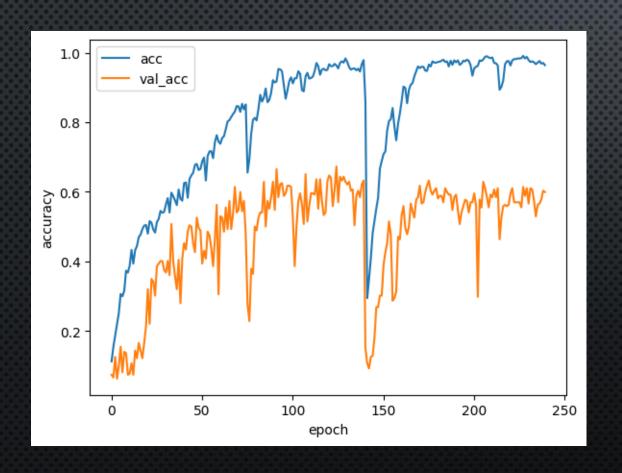
## https://keras.io/api/callbacks/reduce\_lr\_on\_plateau/

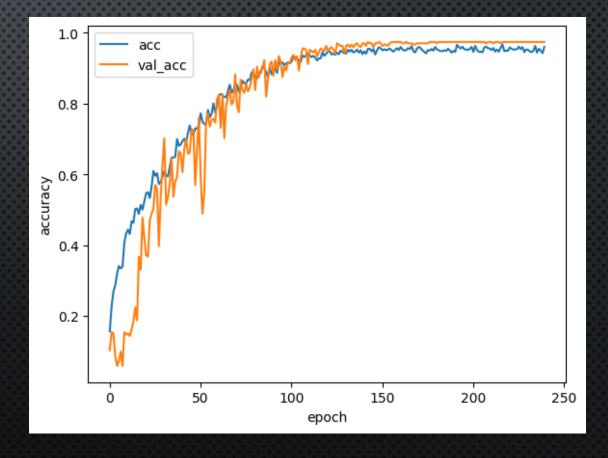
Reduce learning rate when a metric has stopped improving.

Models often benefit from reducing the learning rate by a factor of 2-10 once learning stagnates. This callback monitors a quantity and if no improvement is seen for a 'patience' number of epochs, the learning rate is reduced.

#### **Example**

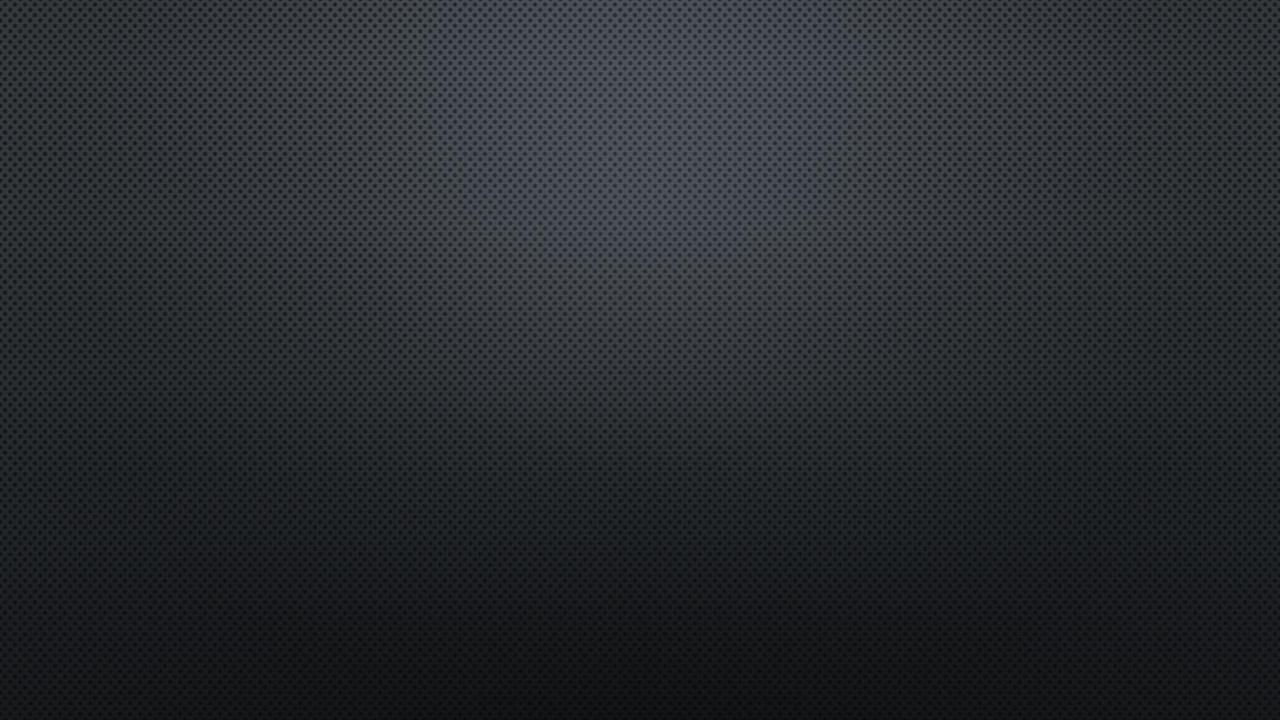
## 仿VGG V1 vs V2





# 數實作

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## 感謝觀賞

Herzlichen Dank für die Aufmerksamkeit

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